

Lookup Tables

Objective

To discuss lookup tables and how to use them to sacrifice storage space to increase computation time.

What Are Lookup Tables

Lookup tables are static arrays that sacrifices memory storage in place of a simple array index lookup of precalculated values. In some examples, a lookup table is not meant to speed a process, but simply an elegant solution to a problem.

Lets look at some examples to see why these are useful.

Why Use Lookup Tables

Simple Example: Convert Potentiometer Voltage to Angle

Lets make some assumptions about the system first:

1. Using an 8-bit ADC
2. Potentiometer is linear
3. Potentiometer sweep angle is 180 or 270 degrees
4. Potentiometer all the way left is 0 deg and 0V
5. Potentiometer all the way right (180/270 deg) is ADC Reference Voltage
6. Using a processor that does NOT have a FPU (**F**loating **P**oint arithmetic **U**nit) like the Arm Cortex M3 we use in the LPC1756.

```
double potADCToDegrees(uint8_t adc)
{
    return ((double)(adc))*(270/256);
}
```

Code Block 1. Without Lookup

```
const double potentiometer_angles[256] =
{
//  [ADC] = Angle
[0] = 0.0,
[1] = 1.0546875,
[2] = 2.109375,
[3] = 3.1640625,
[4] = 4.21875,
[5] = 5.2734375,
[6] = 6.328125,
[7] = 7.3828125,
[8] = 8.4375,
[9] = 9.4921875,
[10] = 10.546875,
[11] = 11.6015625,
[12] = 12.65625,
[13] = 13.7109375,
[14] = 14.765625,
[15] = 15.8203125,
[16] = 16.875,
[17] = 17.9296875,
[18] = 18.984375,
[19] = 20.0390625,
[20] = 21.09375,
[21] = 22.1484375,
[22] = 23.203125,
[23] = 24.2578125,
[24] = 25.3125,
[25] = 26.3671875,
[26] = 27.421875,
[27] = 28.4765625,
[28] = 29.53125,
[29] = 30.5859375,
[30] = 31.640625,
[31] = 32.6953125,
[32] = 33.75,
```

[33] = 34.8046875,
[34] = 35.859375,
[35] = 36.9140625,
[36] = 37.96875,
[37] = 39.0234375,
[38] = 40.078125,
[39] = 41.1328125,
[40] = 42.1875,
[41] = 43.2421875,
[42] = 44.296875,
[43] = 45.3515625,
[44] = 46.40625,
[45] = 47.4609375,
[46] = 48.515625,
[47] = 49.5703125,
[48] = 50.625,
[49] = 51.6796875,
[50] = 52.734375,
[51] = 53.7890625,
[52] = 54.84375,
[53] = 55.8984375,
[54] = 56.953125,
[55] = 58.0078125,
[56] = 59.0625,
[57] = 60.1171875,
[58] = 61.171875,
[59] = 62.2265625,
[60] = 63.28125,
[61] = 64.3359375,
[62] = 65.390625,
[63] = 66.4453125,
[64] = 67.5,
[65] = 68.5546875,
[66] = 69.609375,
[67] = 70.6640625,
[68] = 71.71875,

```
□[69] □= 72.7734375,  
□[70] □= 73.828125,  
□[71] □= 74.8828125,  
□[72] □= 75.9375,  
□[73] □= 76.9921875,  
□[74] □= 78.046875,  
□[75] □= 79.1015625,  
□[76] □= 80.15625,  
□[77] □= 81.2109375,  
□[78] □= 82.265625,  
□[79] □= 83.3203125,  
□[80] □= 84.375,  
□[81] □= 85.4296875,  
□[82] □= 86.484375,  
□[83] □= 87.5390625,  
□[84] □= 88.59375,  
□[85] □= 89.6484375,  
□[86] □= 90.703125,  
□[87] □= 91.7578125,  
□[88] □= 92.8125,  
□[89] □= 93.8671875,  
□[90] □= 94.921875,  
□[91] □= 95.9765625,  
□[92] □= 97.03125,  
□[93] □= 98.0859375,  
□[94] □= 99.140625,  
□[95] □= 100.1953125,  
□[96] □= 101.25,  
□[97] □= 102.3046875,  
□[98] □= 103.359375,  
□[99] □= 104.4140625,  
□[100] □= 105.46875,  
    // ...  
□[240] □= 253.125,  
□[241] □= 254.1796875,  
□[242] □= 255.234375,
```

```

    [243] = 256.2890625,
    [244] = 257.34375,
    [245] = 258.3984375,
    [246] = 259.453125,
    [247] = 260.5078125,
    [248] = 261.5625,
    [249] = 262.6171875,
    [250] = 263.671875,
    [251] = 264.7265625,
    [252] = 265.78125,
    [253] = 266.8359375,
    [254] = 267.890625,
    [255] = 268.9453125,
    [256] = 270
};

inline double potADCToDegrees(uint8_t adc)
{
    return potentiometer_angles[adc]}

```

Code Block 2. With Lookup

With the two examples, it may seem trivial since the *WITHOUT* case is only "really" doing one calculation, multiplying the **uint8_t** with (270/256) since the compiler will most likely optimize this value to its result. But if you take a look at the assembly, the results may shock you.

Look up Table Disassembly

```

00016e08 <main>:
main():
/var/www/html/SJSU-Dev/firmware/Experiements/L5_Application/main.cpp:322
    [254] = 268.9411765,
    [255] = 270
};
int main(void)
{
    16e08:0b082    sub sp, #8
/var/www/html/SJSU-Dev/firmware/Experiements/L5_Application/main.cpp:323
    volatile double a = potentiometer_angles[15];

```

```

16e0a:  a303      add r3, pc, #12; (adr r3, 16e18 <main+0x10>)
16e0c:  e9d3 2300  ldrd r2, r3, [r3]
16e10:  e9cd 2300  strd r2, r3, [sp]
16e14:  e7fe      b.n 16e14 <main+0xc>
16e16:  bf00      nop
16e18:  c3b9a8ae  .word 0xc3b9a8ae 16e1c:  402fc3c3  .word 0x402fc3c3

```

Code Block 3. Dissassembly of Look up Table

Looks about right. You can see at **16e0a** the software is retrieving data from the lookup table, and then it is loading it into the double which is on the stack.

Double Floating Point Disassembly

```

00017c64 <__adddf3>:
__aeabi_dadd():
17c64:  b530      push {r4, r5, lr}
17c66:  ea4f 0441  mov.w r4, r1, lsl #1
17c6a:  ea4f 0543  mov.w r5, r3, lsl #1
17c6e:  ea94 0f05  teq r4, r5
17c72:  bf08      it eq
17c74:  ea90 0f02  teqeq r0, r2
17c78:  bf1f      itttt ne
17c7a:  ea54 0c00  orrsne.w ip, r4, r0
17c7e:  ea55 0c02  orrsne.w ip, r5, r2
17c82:  ea7f 5c64  mvnsne.w ip, r4, asr #21
17c86:  ea7f 5c65  mvnsne.w ip, r5, asr #21
17c8a:  f000 80e2  beq.w 17e52 <__adddf3+0x1ee>
17c8e:  ea4f 5454  mov.w r4, r4, lsr #21
17c92:  ebd4 5555  rsbs r5, r4, r5, lsr #21
17c96:  bfb8      it lt
17c98:  426d      neglt r5, r5
17c9a:  dd0c      ble.n 17cb6 <__adddf3+0x52>
17c9c:  442c      add r4, r5
17c9e:  ea80 0202  eor.w r2, r0, r2
17ca2:  ea81 0303  eor.w r3, r1, r3
17ca6:  ea82 0000  eor.w r0, r2, r0

```

```

17caa:  ea83 0101  eor.w r1, r3, r1
17cae:  ea80 0202  eor.w r2, r0, r2
17cb2:  ea81 0303  eor.w r3, r1, r3
17cb6:  2d36      cmp r5, #54; 0x36
17cb8:  bf88      it hi
17cba:  bd30      pophi {r4, r5, pc}
17cbc:  f011 4f00  tst.w r1, #2147483648; 0x80000000
17cc0:  ea4f 3101  mov.w r1, r1, lsl #12
17cc4:  f44f 1c80  mov.w ip, #1048576; 0x100000
17cc8:  ea4c 3111  orr.w r1, ip, r1, lsr #12
17ccc:  d002      beq.n 17cd4 <__adddf3+0x70>
17cce:  4240      negs r0, r0
17cd0:  eb61 0141  sbc.w r1, r1, r1, lsl #1
17cd4:  f013 4f00  tst.w r3, #2147483648; 0x80000000
17cd8:  ea4f 3303  mov.w r3, r3, lsl #12
17cdc:  ea4c 3313  orr.w r3, ip, r3, lsr #12
17ce0:  d002      beq.n 17ce8 <__adddf3+0x84>
17ce2:  4252      negs r2, r2
17ce4:  eb63 0343  sbc.w r3, r3, r3, lsl #1
17ce8:  ea94 0f05  teq r4, r5
17cec:  f000 80a7  beq.w 17e3e <__adddf3+0x1da>
17cf0:  f1a4 0401  sub.w r4, r4, #1
17cf4:  f1d5 0e20  rsbs lr, r5, #32
17cf8:  db0d      blt.n 17d16 <__adddf3+0xb2>
17cfa:  fa02 fc0e  lsl.w ip, r2, lr
17cfe:  fa22 f205  lsr.w r2, r2, r5
17d02:  1880      adds r0, r0, r2
17d04:  f141 0100  adc.w r1, r1, #0
17d08:  fa03 f20e  lsl.w r2, r3, lr
17d0c:  1880      adds r0, r0, r2
17d0e:  fa43 f305  asr.w r3, r3, r5
17d12:  4159      adcs r1, r3
17d14:  e00e      b.n 17d34 <__adddf3+0xd0>
17d16:  f1a5 0520  sub.w r5, r5, #32
17d1a:  f10e 0e20  add.w lr, lr, #32
17d1e:  2a01      cmp r2, #1

```

```

17d20:  fa03 fc0e  lsl.w ip, r3, lr
17d24:  bf28      itcs
17d26:  f04c 0c02  orrcs.w ip, ip, #2
17d2a:  fa43 f305  asr.w r3, r3, r5
17d2e:  18c0      adds r0, r0, r3
17d30:  eb51 71e3  adcs.w r1, r1, r3, asr #31
17d34:  f001 4500  and.w r5, r1, #2147483648; 0x80000000
17d38:  d507      bpl.n 17d4a <__adddf3+0xe6>
17d3a:  f04f 0e00  mov.w lr, #0
17d3e:  f1dc 0c00  rsbs ip, ip, #0
17d42:  eb7e 0000  sbcs.w r0, lr, r0
17d46:  eb6e 0101  sbc.w r1, lr, r1
17d4a:  f5b1 1f80  cmp.w r1, #1048576; 0x100000
17d4e:  d31b      bcc.n 17d88 <__adddf3+0x124>
17d50:  f5b1 1f00  cmp.w r1, #2097152; 0x200000
17d54:  d30c      bcc.n 17d70 <__adddf3+0x10c>
17d56:  0849      lsr r1, r1, #1
17d58:  ea5f 0030  movs.w r0, r0, rrx
17d5c:  ea4f 0c3c  mov.w ip, ip, rrx
17d60:  f104 0401  add.w r4, r4, #1
17d64:  ea4f 5244  mov.w r2, r4, lsl #21
17d68:  f512 0f80  cmn.w r2, #4194304; 0x400000
17d6c:  f080 809a  bcs.w 17ea4 <__adddf3+0x240>
17d70:  f1bc 4f00  cmp.w ip, #2147483648; 0x80000000
17d74:  bf08      iteq
17d76:  ea5f 0c50  movseq.w ip, r0, lsr #1
17d7a:  f150 0000  adcs.w r0, r0, #0
17d7e:  eb41 5104  adc.w r1, r1, r4, lsl #20
17d82:  ea41 0105  orr.w r1, r1, r5
17d86:  bd30      pop {r4, r5, pc}
17d88:  ea5f 0c4c  movs.w ip, ip, lsl #1
17d8c:  4140      adcs r0, r0
17d8e:  eb41 0101  adc.w r1, r1, r1
17d92:  f411 1f80  tst.w r1, #1048576; 0x100000
17d96:  f1a4 0401  sub.w r4, r4, #1
17d9a:  d1e9      bne.n 17d70 <__adddf3+0x10c>

```

```

17d9c: 0f01 0f00  iteq r1, #0
17da0: bf04      itt eq
17da2: 4601      moveq r1, r0
17da4: 2000      moveq r0, #0
17da6: fab1 f381 clz r3, r1
17daa: bf08      it eq
17dac: 3320      addeq r3, #32
17dae: f1a3 030b sub.w r3, r3, #11
17db2: f1b3 0220 subs.w r2, r3, #32
17db6: da0c      bge.n 17dd2 <__adddf3+0x16e>
17db8: 320c      adds r2, #12
17dba: dd08      ble.n 17dce <__adddf3+0x16a>
17dbc: f102 0c14 add.w ip, r2, #20
17dc0: f1c2 020c rsb r2, r2, #12
17dc4: fa01 f00c lsl.w r0, r1, ip
17dc8: fa21 f102 lsr.w r1, r1, r2
17dcc: e00c      b.n 17de8 <__adddf3+0x184>
17dce: f102 0214 add.w r2, r2, #20
17dd2: bfd8      it le
17dd4: f1c2 0c20 rsble ip, r2, #32
17dd8: fa01 f102 lsl.w r1, r1, r2
17ddc: fa20 fc0c lsr.w ip, r0, ip
17de0: bfdc      itt le
17de2: ea41 010c orrle.w r1, r1, ip
17de6: 4090      lsllle r0, r2
17de8: 1ae4      subs r4, r4, r3
17dea: bfa2      ittt ge
17dec: eb01 5104 addge.w r1, r1, r4, lsl #20
17df0: 4329      orrge r1, r5
17df2: bd30      popge {r4, r5, pc}
17df4: ea6f 0404 mvn.w r4, r4
17df8: 3c1f      subs r4, #31
17dfa: da1c      bge.n 17e36 <__adddf3+0x1d2>
17dfc: 340c      adds r4, #12
17dfe: dc0e      bgt.n 17e1e <__adddf3+0x1ba>
17e00: f104 0414 add.w r4, r4, #20

```

```

17e04: f1c4 0220 rsb r2, r4, #32
17e08: fa20 f004 lsr.w r0, r4
17e0c: fa01 f302 lsl.w r3, r1, r2
17e10: ea40 0003 orr.w r0, r0, r3
17e14: fa21 f304 lsr.w r3, r1, r4
17e18: ea45 0103 orr.w r1, r5, r3
17e1c: bd30      pop {r4, r5, pc}
17e1e: f1c4 040c rsb r4, r4, #12
17e22: f1c4 0220 rsb r2, r4, #32
17e26: fa20 f002 lsr.w r0, r0, r2
17e2a: fa01 f304 lsl.w r3, r1, r4
17e2e: ea40 0003 orr.w r0, r0, r3
17e32: 4629      mov r1, r5
17e34: bd30      pop {r4, r5, pc}
17e36: fa21 f004 lsr.w r0, r1, r4
17e3a: 4629      mov r1, r5
17e3c: bd30      pop {r4, r5, pc}
17e3e: f094 0f00 teq r4, #0
17e42: f483 1380 eor.w r3, r3, #1048576; 0x100000
17e46: bf06      itte eq
17e48: f481 1180 eoreq.w r1, r1, #1048576; 0x100000
17e4c: 3401      addeq r4, #1
17e4e: 3d01      subne r5, #1
17e50: e74e      b.n 17cf0 <__adddf3+0x8c>
17e52: ea7f 5c64 mvns.w ip, r4, asr #21
17e56: bf18      it ne
17e58: ea7f 5c65 mvnsne.w ip, r5, asr #21
17e5c: d029      beq.n 17eb2 <__adddf3+0x24e>
17e5e: ea94 0f05 teq r4, r5
17e62: bf08      it eq
17e64: ea90 0f02 teqeq r0, r2
17e68: d005      beq.n 17e76 <__adddf3+0x212>
17e6a: ea54 0c00 orrs.w ip, r4, r0
17e6e: bf04      itt eq
17e70: 4619      moveq r1, r3
17e72: 4610      moveq r0, r2

```

```

17e74: 0bd30      pop  {r4, r5, pc}
17e76: 0ea91 0f03  teq  r1, r3
17e7a: 0bf1e      ittt  ne
17e7c: 02100      movne r1, #0
17e7e: 02000      movne r0, #0
17e80: 0bd30      popne {r4, r5, pc}
17e82: 0ea5f 5c54  movs.w ip, r4, lsr #21
17e86: 0d105      bne.n 17e94 <__adddf3+0x230>
17e88: 00040      lsls  r0, r0, #1
17e8a: 04149      adcs  r1, r1
17e8c: 0bf28      it  cs
17e8e: 0f041 4100  orrcs.w r1, r1, #2147483648; 0x80000000
17e92: 0bd30      pop  {r4, r5, pc}
17e94: 0f514 0480  adds.w r4, r4, #4194304; 0x400000
17e98: 0bf3c      itt  cc
17e9a: 0f501 1180  addcc.w r1, r1, #1048576; 0x100000
17e9e: 0bd30      popcc {r4, r5, pc}
17ea0: 0f001 4500  and.w r5, r1, #2147483648; 0x80000000
17ea4: 0f045 41fe  orr.w r1, r5, #2130706432; 0x7f000000
17ea8: 0f441 0170  orr.w r1, r1, #15728640; 0xf00000
17eac: 0f04f 0000  mov.w r0, #0
17eb0: 0bd30      pop  {r4, r5, pc}
17eb2: 0ea7f 5c64  mvns.w ip, r4, asr #21
17eb6: 0bf1a      itte  ne
17eb8: 04619      movne r1, r3
17eba: 04610      movne r0, r2
17ebc: 0ea7f 5c65  mvnseq.w ip, r5, asr #21
17ec0: 0bf1c      itt  ne
17ec2: 0460b      movne r3, r1
17ec4: 04602      movne r2, r0
17ec6: 0ea50 3401  orrs.w r4, r0, r1, lsl #12
17eca: 0bf06      itte  eq
17ecc: 0ea52 3503  orrseq.w r5, r2, r3, lsl #12
17ed0: 0ea91 0f03  teqeq r1, r3
17ed4: 0f441 2100  orrne.w r1, r1, #524288; 0x80000
17ed8: 0bd30      pop  {r4, r5, pc}

```

```
17eda:  bf00      nop
```

Code Block 4. Arm Software Floating Point Addition Implementation

This isn't even the full code. This is a function that our calculation function has to run each time it wants to add two doubles together. Also, note that it is not just a straight shot of 202 instructions, because you can see that there are loops in the code where ever you see an instruction's mnemonic that starts with the letter **b** (stands for branch).

Other Use Cases

- Correlate degrees to radians (assuming degrees are whole numbers)
- Table of cosine or sine given radians or degrees
 - In the radians case, you will need to create your own trivial hashing function to convert radians to an index
- Finding a number of bits SET in a 32-bit number
 - Without a lookup table time complexity is $O(n)$ where ($n = 32$), the number of bits you want to look through
 - With a lookup table, the time complexity is $O(1)$, constant time, and only needs the followin operations
 - 3 bitwise left shifts operations
 - 4 bitwise ANDS operations
 - 4 load from memory addresses
 - 4 binary ADD operations
 - Total of 15 operations total

```
/* Found this on wikipedia! */
/* Pseudocode of the lookup table 'uint32_t bits_set[256]' */
/*
    0b00, 0b01, 0b10, 0b11, 0b100, 0b101, ... */
int bits_set[256] = {    0,    1,    1,    2,    1,    2, // 200+ more entries
/* (this code assumes that 'int' is an unsigned 32-bits wide integer) */
int count_ones(unsigned int x) {
    return bits_set[ x      & 255] + bits_set[(x >>  8) & 255]
        + bits_set[(x >> 16) & 255] + bits_set[(x >> 24) & 255]; }
```

Code Block 5. Bits set in a 32-bit number (Found this on wikipedia (look up tables))

There are far more use cases then this, but these are a few.

Lookup Table Decision Tree

Lookup tables can be used as elegant ways to structure information. In this case, they may not provide a speed up but they will associate indexes with something greater, making your code more readable and easier to maintain. In this example, we will be looking at a matrix of function pointers.

Example: Replace Decision Tree

See the function below:

```
void makeADecisionRobot(bool power_system_nominal, bool no_obstacles_ahead)
{
    if(power_system_nominal && no_obstacles_ahead) {
        moveForward();
    }
    else if(power_system_nominal && !no_obstacles_ahead) {
        moveOutOfTheWay();
    }
    else if(!power_system_nominal && no_obstacles_ahead) {
        slowDown();
    }
    else {
        emergencyStop();
    }
}
```

Code Block 6. Typical Decision Tree

```
void (* decision_matrix[2][2])(void) =
{
    [1][1] = moveForward,
    [1][0] = moveOutOfTheWay,
    [0][1] = slowDown,
    [0][0] = emergencyStop,
};

void makeADecisionRobot(bool power_system_nominal, bool no_obstacles_ahead)
{
    decision_matrix[power_system_nominal][no_obstacles_ahead]();
}
```

Code Block 7. Lookup Table Decision Tree

The interesting thing about the decision tree is that it is also more optimal in that, it takes a few instructions to do the look up from memory, then the address of the procedure [function] is looked up and executed, where the former required multiple read instructions and comparison instructions.

This pattern of lookup table will be most useful to us for the interrupts lab assignment.

Revision #11

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